# t com





## / Model-based learning for location-to-channel mapping /

Baptiste CHATELIER<sup>‡,†,\*</sup>, Luc LE MAGOAROU<sup>†,\*</sup>, Vincent CORLAY<sup>‡,\*</sup>, Matthieu CRUSSIERE<sup>†,\*</sup>

† Univ Rennes, INSA Rennes, CNRS, IETR-UMR 6164, Rennes, France
 ‡ Mitsubishi Electric R&D Centre Europe, Rennes, France
 \* b<>com, Rennes, France

baptiste.chatelier@insa-rennes.fr





- Typical data processing setting:
  - We observe a *large* number of *correlated* variables, explained by a *small* number of *independent* factors.





- Typical data processing setting:
  - We observe a *large* number of *correlated* variables, explained by a *small* number of *independent* factors.

There are two complementary approaches to handle this situation:





- Typical data processing setting:
  - We observe a *large* number of *correlated* variables, explained by a *small* number of *independent* factors.

There are two complementary approaches to handle this situation:

### Signal processing

- Model based
- Large bias
- Low complexity



- Typical data processing setting:
  - We observe a *large* number of *correlated* variables, explained by a *small* number of *independent* factors.

There are two complementary approaches to handle this situation:

### Signal processing

- Model based
- Large bias
- Low complexity

### • ML/AI

- Data based
- Low bias
- High complexity

< Model-based AI >

- Typical data processing setting:
  - We observe a *large* number of *correlated* variables, explained by a *small* number of *independent* factors.

There are two complementary approaches to handle this situation:

- Signal processing
  - Model based
  - Large bias
  - Low complexity

### • ML/AI

- Data based
- Low bias
- High complexity

### Hybrid approach: Model-based AI

Use models to structure, initialize and train learning methods



Make models more flexible: reduce bias of signal processing methods ۰

There are two complementary approaches to handle this situation:

- Use models to structure, initialize and train learning methods
- High complexity Hybrid approach: Model-based Al

### Signal processing Model based

- Large bias
- Low complexity

### ML/AI

- Data based

- Low bias

< Model-based AI >

- Typical data processing setting:
  - We observe a *large* number of *correlated* variables, explained by a *small* number of independent factors.



Guide machine learning methods: reduce their complexity

Make models more flexible: reduce bias of signal processing methods

Use models to structure, initialize and train learning methods

There are two complementary approaches to handle this situation:

### Signal processing

- Model based
- Large bias

۲

Low complexity

### ML/AI

- Data based
- Low bias
- High complexity

### Hybrid approach: Model-based Al

We observe a *large* number of *correlated* variables, explained by a *small* number of





Typical data processing setting:

independent factors.



• In a SISO-monocarrier setting, the channel can be expressed as:



- In a SISO-monocarrier setting, the channel can be expressed as:
  - Hypothesis: attenuation/phase proportional to propagation distance





- In a SISO-monocarrier setting, the channel can be expressed as:
  - · Hypothesis: attenuation/phase proportional to propagation distance





• How to learn the location-to-channel mapping ?



- How to learn the location-to-channel mapping ?
- Use of the Implicit Neural Representation (INR) concept:



- How to learn the location-to-channel mapping ?
- Use of the Implicit Neural Representation (INR) concept:
  - Neural networks are universal function approximators<sup>1,2</sup>

<sup>&</sup>lt;sup>1</sup>Hornik, Stinchcombe, and White, "Multilayer feedforward networks are universal approximators". <sup>2</sup>Cybenko, "Approximation by superpositions of a sigmoidal function".



- How to learn the location-to-channel mapping ?
- Use of the Implicit Neural Representation (INR) concept:
  - Neural networks are universal function approximators<sup>1,2</sup>
  - Using x, one can design and train a neural network in a supervised manner to learn a representation of  $h\left( {\bf x} \right)$

<sup>&</sup>lt;sup>1</sup>Hornik, Stinchcombe, and White, "Multilayer feedforward networks are universal approximators". <sup>2</sup>Cybenko, "Approximation by superpositions of a sigmoidal function".



- How to learn the location-to-channel mapping ?
- Use of the Implicit Neural Representation (INR) concept:
  - Neural networks are universal function approximators<sup>1,2</sup>
  - Using x, one can design and train a neural network in a supervised manner to learn a representation of  $h\left(\mathbf{x}\right)$
- Goal: learn

$$\begin{aligned} f_{\boldsymbol{\theta}} \colon \mathbb{R}^2 &\longrightarrow \mathbb{C} \\ \mathbf{x} &\longrightarrow h\left(\mathbf{x}\right), \end{aligned} \tag{3}$$

<sup>&</sup>lt;sup>1</sup>Hornik, Stinchcombe, and White, "Multilayer feedforward networks are universal approximators". <sup>2</sup>Cybenko, "Approximation by superpositions of a sigmoidal function".



- How to learn the location-to-channel mapping ?
- Use of the Implicit Neural Representation (INR) concept:
  - Neural networks are universal function approximators
  - Using  ${\bf x},$  one can design and train a neural network in a supervised manner to learn a representation of  $h\left( {\bf x} \right)$
- Goal: learn

$$\begin{aligned} f_{\boldsymbol{\theta}} \colon \mathbb{R}^2 &\longrightarrow \mathbb{C} \\ \mathbf{x} &\longrightarrow h\left(\mathbf{x}\right), \end{aligned} \tag{3}$$

### How to efficiently learn $f_{\boldsymbol{\theta}}\left(\mathbf{x}\right)$ ?





Classical architecture (MLPs) are biased towards learning low frequency content<sup>1,2</sup>

<sup>&</sup>lt;sup>1</sup>Rahaman et al., "On the spectral bias of neural networks". <sup>2</sup>Cao et al., "Towards Understanding the Spectral Bias of Deep Learning".





Classical architecture (MLPs) are biased towards learning low frequency content<sup>1,2</sup>

$$h\left(\mathbf{x}\right) = \sum_{l=1}^{L_p} \frac{\alpha_l \mathrm{e}^{\mathrm{j}\beta_l}}{\|\mathbf{x} - \mathbf{x}_l\|_2} \mathrm{e}^{-\mathrm{j}\frac{2\pi}{\lambda}\|\mathbf{x} - \mathbf{x}_l\|_2} \tag{4}$$

 High frequency spatial dependence due to the exponential argument: small change in x leads to a huge change in h (x) → on the order of the wavelength

<sup>&</sup>lt;sup>1</sup>Rahaman et al., "On the spectral bias of neural networks".

<sup>&</sup>lt;sup>2</sup>Cao et al., "Towards Understanding the Spectral Bias of Deep Learning".





Classical architecture (MLPs) are biased towards learning low frequency content<sup>1,2</sup>

$$h\left(\mathbf{x}\right) = \sum_{l=1}^{L_p} \frac{\alpha_l \mathrm{e}^{\mathrm{j}\beta_l}}{\|\mathbf{x} - \mathbf{x}_l\|_2} \mathrm{e}^{-\mathrm{j}\frac{2\pi}{\lambda}\|\mathbf{x} - \mathbf{x}_l\|_2} \tag{4}$$

 High frequency spatial dependence due to the exponential argument: small change in x leads to a huge change in h (x) → on the order of the wavelength

### How to learn $f_{\theta}(\mathbf{x})$ without suffering from the spectral bias ?

<sup>&</sup>lt;sup>1</sup>Rahaman et al., "On the spectral bias of neural networks".

<sup>&</sup>lt;sup>2</sup>Cao et al., "Towards Understanding the Spectral Bias of Deep Learning".





Derive a model-based architecture for the location-to-channel mapping learning





- Derive a model-based architecture for the location-to-channel mapping learning
  - Where the model does not have to learn high frequency spatial content





- Derive a model-based architecture for the location-to-channel mapping learning
  - Where the model does not have to learn high frequency spatial content
- Show that this model-based approach overcomes the spectral bias, and successfully learns the location-to-channel mapping



• The mapping is hard to learn due to the high frequency spatial content



- The mapping is hard to learn due to the high frequency spatial content
- Idea: split high frequency from low frequency spatial content with a Taylor expansion



- The mapping is hard to learn due to the high frequency spatial content
- Idea: split high frequency from low frequency spatial content with a Taylor expansion
- Around a reference point  $\mathbf{x}_r \in \mathbb{R}^2$ :

$$\|\mathbf{x} - \mathbf{x}_l\|_2 \simeq \|\mathbf{x}_r - \mathbf{x}_l\|_2 + \mathbf{u}_{(\mathbf{x}_r - \mathbf{x}_l)} \cdot (\mathbf{x} - \mathbf{x}_r)$$
(5)



- The mapping is hard to learn due to the high frequency spatial content
- Idea: split high frequency from low frequency spatial content with a Taylor expansion
- Around a reference point  $\mathbf{x}_r \in \mathbb{R}^2$ :

$$\|\mathbf{x} - \mathbf{x}_l\|_2 \simeq \|\mathbf{x}_r - \mathbf{x}_l\|_2 + \mathbf{u}_{(\mathbf{x}_r - \mathbf{x}_l)} \cdot (\mathbf{x} - \mathbf{x}_r)$$
(5)

$$\mathbf{x}_r^{\boldsymbol{ imes}}$$
  
 $\mathbf{x}^{\boldsymbol{ imes}} \qquad \mathbf{x}_l$ 



- The mapping is hard to learn due to the high frequency spatial content
- Idea: split high frequency from low frequency spatial content with a Taylor expansion
- Around a reference point  $\mathbf{x}_r \in \mathbb{R}^2$ :

 $\|$ 

$$\mathbf{x} - \mathbf{x}_{l} \|_{2} \simeq \|\mathbf{x}_{r} - \mathbf{x}_{l}\|_{2} + \mathbf{u}_{(\mathbf{x}_{r} - \mathbf{x}_{l})} \cdot (\mathbf{x} - \mathbf{x}_{r})$$

$$\mathbf{x}_{r}^{\mathbf{X}}$$

$$\mathbf{x}_{r}^{\mathbf{X}}$$

$$\mathbf{x}_{r}^{\mathbf{X}} \mathbf{x}_{l}$$

$$(5)$$



- The mapping is hard to learn due to the high frequency spatial content
- Idea: split high frequency from low frequency spatial content with a Taylor expansion
- Around a reference point  $\mathbf{x}_r \in \mathbb{R}^2$ :

 $\|$ 

$$\mathbf{x} - \mathbf{x}_{l} \|_{2} \simeq \|\mathbf{x}_{r} - \mathbf{x}_{l}\|_{2} + \mathbf{u}_{(\mathbf{x}_{r} - \mathbf{x}_{l})} \cdot (\mathbf{x} - \mathbf{x}_{r})$$
(5)  
$$\mathbf{x}_{r} \|\mathbf{x}_{r} - \mathbf{x}_{l}\|_{2}$$
$$\mathbf{x}_{l} \|\mathbf{x}_{r} - \mathbf{x}_{l}\|_{2}$$



- The mapping is hard to learn due to the high frequency spatial content
- Idea: split high frequency from low frequency spatial content with a Taylor expansion
- Around a reference point  $\mathbf{x}_r \in \mathbb{R}^2$ :

$$\|\mathbf{x} - \mathbf{x}_l\|_2 \simeq \|\mathbf{x}_r - \mathbf{x}_l\|_2 + \mathbf{u}_{(\mathbf{x}_r - \mathbf{x}_l)} \cdot (\mathbf{x} - \mathbf{x}_r)$$
(5)





- The mapping is hard to learn due to the high frequency spatial content
- Idea: split high frequency from low frequency spatial content with a Taylor expansion
- Around a reference point  $\mathbf{x}_r \in \mathbb{R}^2$ :

$$\|\mathbf{x} - \mathbf{x}_l\|_2 \simeq \|\mathbf{x}_r - \mathbf{x}_l\|_2 + \mathbf{u}_{(\mathbf{x}_r - \mathbf{x}_l)} \cdot (\mathbf{x} - \mathbf{x}_r)$$
(5)





- The mapping is hard to learn due to the high frequency spatial content
- Idea: split high frequency from low frequency spatial content with a Taylor expansion
- Around a reference point  $\mathbf{x}_r \in \mathbb{R}^2$ :

$$\|\mathbf{x} - \mathbf{x}_l\|_2 \simeq \|\mathbf{x}_r - \mathbf{x}_l\|_2 + \mathbf{u}_{(\mathbf{x}_r - \mathbf{x}_l)} \cdot (\mathbf{x} - \mathbf{x}_r)$$
(5)





- The mapping is hard to learn due to the high frequency spatial content
- Idea: split high frequency from low frequency spatial content with a Taylor expansion
- Around a reference point  $\mathbf{x}_r \in \mathbb{R}^2$ :

$$\|\mathbf{x} - \mathbf{x}_l\|_2 \simeq \|\mathbf{x}_r - \mathbf{x}_l\|_2 + \mathbf{u}_{(\mathbf{x}_r - \mathbf{x}_l)} \cdot (\mathbf{x} - \mathbf{x}_r)$$
(5)



- The mapping is hard to learn due to the high frequency spatial content
- Idea: split high frequency from low frequency spatial content with a Taylor expansion
- Around a reference point  $\mathbf{x}_r \in \mathbb{R}^2$ :

$$\|\mathbf{x} - \mathbf{x}_l\|_2 \simeq \|\mathbf{x}_r - \mathbf{x}_l\|_2 + \mathbf{u}_{(\mathbf{x}_r - \mathbf{x}_l)} \cdot (\mathbf{x} - \mathbf{x}_r)$$
(5)

 $\mathbf{x} \not\models \begin{bmatrix} \mathbf{x}_r - \mathbf{x}_l \\ \mathbf{x}_r \\ \vdots \\ \mathbf{x}_r \\ \vdots \\ \mathbf{x}_l \end{bmatrix}_{\mathbf{x}_l}$ 



- The mapping is hard to learn due to the high frequency spatial content
- Idea: split high frequency from low frequency spatial content with a Taylor expansion
- Around a reference point  $\mathbf{x}_r \in \mathbb{R}^2$ :

$$\|\mathbf{x} - \mathbf{x}_l\|_2 \simeq \|\mathbf{x}_r - \mathbf{x}_l\|_2 + \mathbf{u}_{(\mathbf{x}_r - \mathbf{x}_l)} \cdot (\mathbf{x} - \mathbf{x}_r)$$
(5)





- The mapping is hard to learn due to the high frequency spatial content
- Idea: split high frequency from low frequency spatial content with a Taylor expansion
- Around a reference point  $\mathbf{x}_r \in \mathbb{R}^2$ :

$$\|\mathbf{x} - \mathbf{x}_l\|_2 \simeq \|\mathbf{x}_r - \mathbf{x}_l\|_2 + \mathbf{u}_{(\mathbf{x}_r - \mathbf{x}_l)} \cdot (\mathbf{x} - \mathbf{x}_r)$$
(5)




- The mapping is hard to learn due to the high frequency spatial content
- Idea: split high frequency from low frequency spatial content with a Taylor expansion
- Around a reference point  $\mathbf{x}_r \in \mathbb{R}^2$ :

$$\|\mathbf{x} - \mathbf{x}_l\|_2 \simeq \|\mathbf{x}_r - \mathbf{x}_l\|_2 + \mathbf{u}_{(\mathbf{x}_r - \mathbf{x}_l)} \cdot (\mathbf{x} - \mathbf{x}_r)$$
(5)

• This yields:

$$h\left(\mathbf{x}\right) \simeq \sum_{l=1}^{L_{p}} \underbrace{\frac{\alpha_{l} \mathrm{e}^{\mathrm{j}\beta_{l}} h_{l}\left(\mathbf{x}_{r}\right) \mathrm{e}^{\mathrm{j}\frac{2\pi}{\lambda}\mathbf{u}_{\left(\mathbf{x}_{r}-\mathbf{x}_{l}\right)}\cdot\mathbf{x}_{r}}}{1 + \frac{\mathbf{u}_{\left(\mathbf{x}_{r}-\mathbf{x}_{l}\right)}\cdot\left(\mathbf{x}-\mathbf{x}_{r}\right)}{\|\mathbf{x}_{r}-\mathbf{x}_{l}\|_{2}}}_{\text{Slowly varying}} \mathrm{e}^{-\mathrm{j}\frac{2\pi}{\lambda}\mathbf{u}_{\left(\mathbf{x}_{r}-\mathbf{x}_{l}\right)}\cdot\mathbf{x}}}_{\text{Fastly varying}}$$

(6)



- The mapping is hard to learn due to the high frequency spatial content
- Idea: split high frequency from low frequency spatial content with a Taylor expansion
- Around a reference point  $\mathbf{x}_r \in \mathbb{R}^2$ :

$$\|\mathbf{x} - \mathbf{x}_l\|_2 \simeq \|\mathbf{x}_r - \mathbf{x}_l\|_2 + \mathbf{u}_{(\mathbf{x}_r - \mathbf{x}_l)} \cdot (\mathbf{x} - \mathbf{x}_r)$$
(5)

• This yields:

$$h\left(\mathbf{x}\right) \simeq \sum_{l=1}^{L_{p}} \underbrace{\frac{\alpha_{l} \mathrm{e}^{\mathrm{j}\beta_{l}} h_{l}\left(\mathbf{x}_{r}\right) \mathrm{e}^{\mathrm{j}\frac{2\pi}{\lambda}\mathbf{u}_{\left(\mathbf{x}_{r}-\mathbf{x}_{l}\right)\cdot\mathbf{x}_{r}}}}{1 + \frac{\mathbf{u}_{\left(\mathbf{x}_{r}-\mathbf{x}_{l}\right)\cdot\left(\mathbf{x}-\mathbf{x}_{r}\right)}}{\|\mathbf{x}_{r}-\mathbf{x}_{l}\|_{2}}} \mathrm{e}^{-\mathrm{j}\frac{2\pi}{\lambda}\mathbf{u}_{\left(\mathbf{x}_{r}-\mathbf{x}_{l}\right)\cdot\mathbf{x}}}{\mathrm{Fastly varying}}}$$
(6)

 $h\left(\mathbf{x}
ight)$  is locally approximated as a linear combination of planar wavefronts













































• One needs a set of spatial frequencies per hexagon:



- One needs a set of spatial frequencies per hexagon:
  - $\Psi(\mathbf{x}) = \{\psi_i(\mathbf{x})\}_{i=1}^D = \{e^{-j\mathbf{k}_i \cdot \mathbf{x}}\}_{i=1}^D$ : dictionary containing well-chosen planar wavefronts



- One needs a set of spatial frequencies per hexagon:
  - $\Psi(\mathbf{x}) = \{\psi_i(\mathbf{x})\}_{i=1}^D = \{e^{-j\mathbf{k}_i \cdot \mathbf{x}}\}_{i=1}^D$ : dictionary containing well-chosen planar wavefronts
    - Can be constructed by sampling the unit circle with D spatial frequencies



- One needs a set of spatial frequencies per hexagon:
  - $\Psi(\mathbf{x}) = \left\{\psi_i(\mathbf{x})\right\}_{i=1}^D = \left\{e^{-j\mathbf{k}_i\cdot\mathbf{x}}\right\}_{i=1}^D$ : dictionary containing well-chosen planar wavefronts
    - Can be constructed by sampling the unit circle with D spatial frequencies
  - $\mathbf{w}(\mathbf{x}) \in \mathbb{C}^{D}$ : location-dependent activation vector



- One needs a set of spatial frequencies per hexagon:
  - $\Psi(\mathbf{x}) = \{\psi_i(\mathbf{x})\}_{i=1}^D = \{e^{-j\mathbf{k}_i \cdot \mathbf{x}}\}_{i=1}^D$ : dictionary containing well-chosen planar wavefronts
    - Can be constructed by sampling the unit circle with D spatial frequencies
  - $\mathbf{w}(\mathbf{x}) \in \mathbb{C}^{D}$ : location-dependent activation vector

$$\forall \mathbf{x} \in \mathbb{R}^{2}, \ h\left(\mathbf{x}\right) \simeq \sum_{i=1}^{D} w_{i}\left(\mathbf{x}\right) \psi_{i}\left(\mathbf{x}\right),$$

$$\text{with} \left\|\mathbf{w}\left(\mathbf{x}\right)\right\|_{0} = L_{p}$$

$$(7)$$



- One needs a set of spatial frequencies per hexagon:
  - $\Psi(\mathbf{x}) = \{\psi_i(\mathbf{x})\}_{i=1}^D = \{e^{-j\mathbf{k}_i \cdot \mathbf{x}}\}_{i=1}^D$ : dictionary containing well-chosen planar wavefronts
    - Can be constructed by sampling the unit circle with D spatial frequencies
  - $\mathbf{w}(\mathbf{x}) \in \mathbb{C}^{D}$ : location-dependent activation vector

$$\forall \mathbf{x} \in \mathbb{R}^{2}, \ h\left(\mathbf{x}\right) \simeq \sum_{i=1}^{D} w_{i}\left(\mathbf{x}\right) \psi_{i}\left(\mathbf{x}\right),$$
with  $\|\mathbf{w}\left(\mathbf{x}\right)\|_{0} = L_{p}$ 
(7)

The local planar approximation becomes global with a well-chosen dictionary





• Main idea: for a given input location  $\mathbf{x} \in \mathbb{R}^2$ 





- Main idea: for a given input location  $\mathbf{x} \in \mathbb{R}^2$ 
  - From fixed spatial frequencies  $\{\mathbf{k}_i\}_{i=1}^D$  compute Fourier features  $\{e^{-j\mathbf{k}_i \cdot \mathbf{x}}\}_{i=1}^D$





- Main idea: for a given input location  $\mathbf{x} \in \mathbb{R}^2$ 
  - From fixed spatial frequencies  $\{\mathbf{k}_i\}_{i=1}^D$  compute Fourier features  $\{e^{-j\mathbf{k}_i\cdot\mathbf{x}}\}_{i=1}^D$
  - Compute the associated complex weights  $\mathbf{w}(\mathbf{x})$ , with the sparsity constraint







• Channel generation:





- Channel generation:
  - $f_0 = 3.5 \text{GHz}$



- Channel generation:
  - $f_0 = 3.5 \text{GHz}$
  - Synthetic, with hand-placed virtual sources



- Channel generation:
  - $f_0 = 3.5 \text{GHz}$
  - Synthetic, with hand-placed virtual sources
  - Ray-tracing (Sionna) in Paris



- Channel generation:
  - $f_0 = 3.5 \text{GHz}$
  - Synthetic, with hand-placed virtual sources
  - Ray-tracing (Sionna) in Paris

Locations generation:



- Channel generation:
  - $f_0 = 3.5 \text{GHz}$
  - Synthetic, with hand-placed virtual sources
  - Ray-tracing (Sionna) in Paris

- Locations generation:
  - 10m by 10m square scene



- Channel generation:
  - $f_0 = 3.5 \text{GHz}$
  - Synthetic, with hand-placed virtual sources
  - Ray-tracing (Sionna) in Paris

- Locations generation:
  - 10m by 10m square scene
  - Train/test locations randomly dropped in the scene with a certain spatial density



- Channel generation:
  - $f_0 = 3.5 \text{GHz}$
  - Synthetic, with hand-placed virtual sources
  - Ray-tracing (Sionna) in Paris

- Locations generation:
  - 10m by 10m square scene
  - Train/test locations randomly dropped in the scene with a certain spatial density
  - Evaluation locations:  $\lambda/4$  uniform grid



- Channel generation:
  - $f_0 = 3.5 \text{GHz}$
  - Synthetic, with hand-placed virtual sources
  - Ray-tracing (Sionna) in Paris

- Locations generation:
  - 10m by 10m square scene
  - Train/test locations randomly dropped in the scene with a certain spatial density
  - Evaluation locations:  $\lambda/4$  uniform grid

• Train loss:

$$\mathcal{L} = \mathbb{E}\left[\left\|f_{\boldsymbol{\theta}}\left(\mathbf{x}\right) - h\left(\mathbf{x}\right)\right\|_{2}^{2}\right], \mathbf{x} \in \mathcal{D} \subset \mathbb{R}^{2},$$
(8)

with  $\mathcal{D}$ : batch locations set



- Channel generation:
  - $f_0 = 3.5 \text{GHz}$
  - Synthetic, with hand-placed virtual sources
  - Ray-tracing (Sionna) in Paris

- Locations generation:
  - 10m by 10m square scene
  - Train/test locations randomly dropped in the scene with a certain spatial density
  - Evaluation locations:  $\lambda/4$  uniform grid

• Train loss:

$$\mathcal{L} = \mathbb{E}\left[\left\|f_{\boldsymbol{\theta}}\left(\mathbf{x}\right) - h\left(\mathbf{x}\right)\right\|_{2}^{2}\right], \mathbf{x} \in \mathcal{D} \subset \mathbb{R}^{2},$$
(8)

with  $\mathcal{D}$ : batch locations set

• Evaluation metric:

$$\mathsf{NMSE} = 10 \log_{10} \left( \frac{\|h(\mathbf{x}) - f_{\boldsymbol{\theta}}(\mathbf{x})\|_{2}^{2}}{\|h(\mathbf{x})\|_{2}^{2}} \right), \mathbf{x} \in \mathcal{E} \subset \mathbb{R}^{2}$$
(9)

with  $\ensuremath{\mathcal{E}}$  : evaluation locations set







• 1. MLP, 2. RFF, 3. RFF lin.



- Synthetic channels,  $L_p = 6$  propagation paths
- Train loc. density:  $100 \text{locs./m}^2 \simeq 0.7 \; \text{locs./} \lambda^2$



- Synthetic channels,  $L_p = 6$  propagation paths
- Train loc. density: 100locs./m<sup>2</sup>  $\simeq 0.7$  locs./ $\lambda^2$

	MLP	RFF	RFF lin.	Proposed
Params.	16.8M	33.1 <b>M</b>	4k	0.5M
NMSE <sub>(dB)</sub>	0.16	-3.30	-3.04	-20.60



- Synthetic channels,  $L_p = 6$  propagation paths
- Train loc. density: 100locs./m<sup>2</sup>  $\simeq 0.7$  locs./ $\lambda^2$



• Small zone (2.5m by 2.5m)


- Ray-tracing channels,  $L_p = 11$  propagation paths
- Train loc. density:  $150 \text{locs./m}^2 \simeq 1.1 \; \text{locs./} \lambda^2$



- Ray-tracing channels,  $L_p = 11$  propagation paths
- Train loc. density:  $150 \text{locs./m}^2 \simeq 1.1 \text{ locs./}\lambda^2$

	MLP	RFF	RFF lin.	Proposed
Params.	16.8M	33.1M	4k	0.5M
NMSE <sub>(dB)</sub>	0.14	-2.41	-2.21	-23.41



- Ray-tracing channels,  $L_p = 11$  propagation paths
- Train loc. density:  $150 \text{locs.}/\text{m}^2 \simeq 1.1 \text{ locs.}/\lambda^2$



• Small zone (2.5m by 2.5m)



• Synthetic channels, variable training loc. density, variable propagation path number



- Synthetic channels, variable training loc. density, variable propagation path number
- For each point: 100 training with random virtual sources







• Contributions:





- Contributions:
  - Derive a model-based neural network to learn the location-to-channel mapping





- Contributions:
  - Derive a model-based neural network to learn the location-to-channel mapping
  - · Show that the proposed model-based architecture allows to overcome the spectral bias





- Contributions:
  - · Derive a model-based neural network to learn the location-to-channel mapping
  - · Show that the proposed model-based architecture allows to overcome the spectral bias
  - · Better performance than baselines, with less training parameters





- Contributions:
  - · Derive a model-based neural network to learn the location-to-channel mapping
  - · Show that the proposed model-based architecture allows to overcome the spectral bias
  - · Better performance than baselines, with less training parameters
- Future work:





- Contributions:
  - Derive a model-based neural network to learn the location-to-channel mapping
  - · Show that the proposed model-based architecture allows to overcome the spectral bias
  - · Better performance than baselines, with less training parameters
- Future work:
  - · Adapt the architecture to a more realistic scenario: multi-antenna/multicarrier





- Contributions:
  - Derive a model-based neural network to learn the location-to-channel mapping
  - · Show that the proposed model-based architecture allows to overcome the spectral bias
  - Better performance than baselines, with less training parameters
- Future work:
  - · Adapt the architecture to a more realistic scenario: multi-antenna/multicarrier
- Link to paper: https://arxiv.org/pdf/2308.14370.pdf

## Thanks